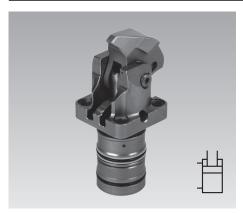


## **Compact Clamps**

## Cartridge type, pneumatic position monitoring optional, double acting, max. operating pressure 250 bar



## **Application**

Compact clamps are designed for application in hydraulic clamping fixtures where oil supply is effected through drilled channels in the fixture body.

Due to the minimum space required, the compact clamp is especially suitable for clamping fixtures with little space for the installation of hydraulic clamping elements.

A clamping recess in the workpiece a little bit wider than the clamping lever is sufficient as clamping surface. Typical applications are:

- Rotary indexing fixtures in horizontal and vertical machining centres
- Clamping fixtures for machining of several sides and complete machining
- · Multiple clamping fixtures with many workpieces that are closely arranged
- Test systems for motors, gears, etc.
- Assembly lines

#### **Description**

The hydraulic compact clamp is a double-acting pull-type cylinder where a part of the linear stroke is used to swing the clamping lever onto the workpiece.

The version with cover is inserted in open bore holes and enables the smallest possible build-

The version without cover requires a closed pocket hole.

#### **Available versions**

## 1. With pneumatic

#### clamping monitoring 180X1XX

The clamping monitoring signals:

"The clamping lever is within the usable clamping range and the workpiece is clamped with minimum clamping force (min. 70 bar)."

#### 2. With pneumatic 180X1XXA unclamping monitoring

The unclamping monitoring signals:

"The clamping lever is within the unclamping range, starting approx. 10° before the final position."

#### 3. Without position monitoring 180X 1XXB

Pneumatic position monitoring see page 6

Important notes (see page 5)

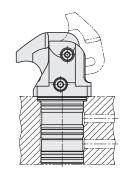
#### **Advantages**

- Minimum dimensions
- Partially immersed body
- Mounting without pipes
- Metallic wiper edge for piston rod
- Clamping lever can be swivelled into small recesses
- Workpiece clamping without any side loads
- Unimpeded loading and unloading of the clamping fixture
- Long clamping lever adaptable to the workpiece
- Universal clamping lever for adapting customised clamping levers
- Mounting position: any

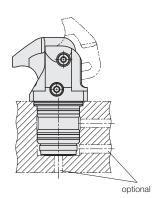
#### Installation and connecting possibilities

#### **Drilled channels**

with cover

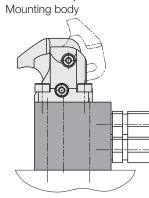


#### without cover

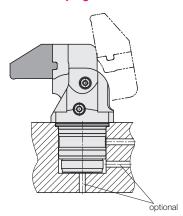


## Pipe thread

with accessory

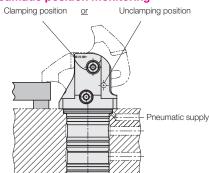


#### **Universal clamping lever**



#### Long clamping lever (blank)

## **Pneumatic position monitoring**



## Application example

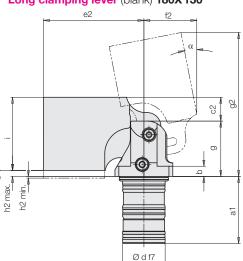


Clamping of a cast part

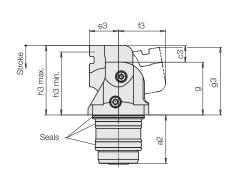
## With cover Short clamping lever 180X 110

# Lever length E. a, Ødf7

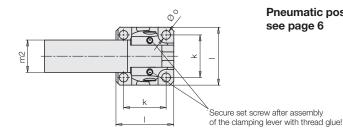
## Long clamping lever (blank) 180X 130



## Without cover **Universal clamping lever 180X 150**

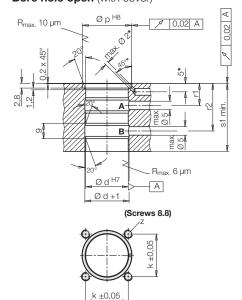






Pneumatic position monitoring see page 6

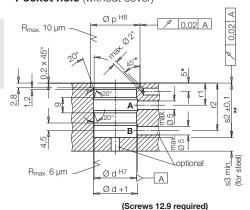
## Bore hole open (with cover)



## Materials

Body	hardened, stainless
Clamping lever: short long (blank)	HRc 48 – 55, stainless X37 Cr Mo V5-1 hardened and tempered HRc 40 and nitrated
Seals	NBR and PUR (max. 80°C)

## Pocket hole (without cover)



#### Accessories

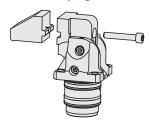
Mounting body (see page 4)

- **A** = Clamping **B** = Unclamping
- Bore holes for pneumatic clamping and
- \*\* Dimension s2 ±0.1 must be met, as the bottom of the pocket hole is the lower stop for the piston.

## unclamping monitoring, only if required.

## k ±0,05 k ±0,05

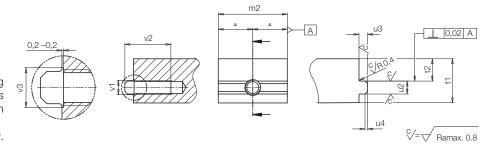
## **Universal clamping lever**



The compact clamp with universal clamping lever and integrated swing mechanism enables the fixing of customised clamping levers, which are relatively easy to manufacture.

The fixing screw 12.9 included in our delivery. Tightening torque see chart page 3.

## Connecting dimensions to the flange of the universal clamping lever

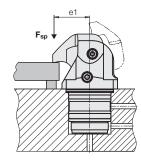


## **Technical Data**

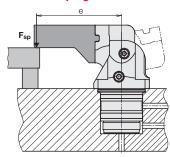
Size		1	2	3	4
Clamping force at 250 bar (short clamping lever) [kN		3.2	4.5	7.5	11.5
Vlax. stroke	[mm]	5	5	7	8.5
Clamping stroke, usable	[mm]	4.5	4.5	6.5	8
Piston Ø/piston rod Ø	[mm]	18 / 11	22 / 14	28 / 17	33 / 19
Dil volume clamping/unclamping	[cm <sup>3</sup> ]	2.3 / 3.6	3.2 / 5.4	6.4 / 10.2	10.5 / 15.7
Max. flow rate	[cm <sup>3</sup> /s]	8	11	22	35
Minimum pressure without clamping monitoring	[bar]	20	20	20	20
with clamping monitoring	[bar]	70	70	70	70
with unclamping monitoring	[bar]	20	20	20	20
Min. air pressure	[bar]	3	3	3	3
x ±1	[°]	13.5	10.5	14	16
a1	[mm]	39.4	43	48.5	50.5
a2	[mm]	32	34	40.6	40.8
)	[mm]	6	7	10	10
21	[mm]	5	5	7	8.5
52	[mm]	14	12	7	8.5
53	[mm]	14	16	16	22.5
30 0d H7/f7		25	32	40	45
	[mm]				
2	[mm]	27	28	36.5	36.5
2	[mm]	59	60	67.5	67.5
3	[mm]	17	20	22	22
1	[mm]	24,7	25,9	31,3	33,8
2	[mm]	30,7	30,5	31,3	33,8
3	[mm]	34,3	37	40,4	48,1
1	[mm]	32,5	36,5	43	46
, 1 max.*	[mm]	49,3	51	63	64,8
2 min./max.*	[mm]	85 / 87,5	86/89,5	97,7/99,7	100,9/103
g3	[mm]	44	47,2	55,4	60,6
n1 min. / h1 max.	[mm]	15.5 / 20	15.5 / 20	15.5 / 22	15.5 / 23.5
n2 min. / h2 max.	[mm]	1 / 3.5	2 / 2.5	1 / 5.5	1 / 7
13 min. / h3 max.	[mm]	42 / 46.5	48 / 52.5	52.5 / 59	60.5 / 68.5
io min. / no max.	[mm]	43	46 46	44.5	47.5
		25	31	36.5	
	[mm]				41
	[mm]	34	42	48	55
11	[mm]	5	6	8	8
12	[mm]	21	26	32	35
	[°]	50.4	55.8	56.1	62
Ø o	[mm]	5.2	6.2	6.2	8.2
9 H g (8	[mm]	29	36	44	49
1	[mm]	13	13	14	14
2	[mm]	28	28	31	31
s1 min.	[mm]	40	43.5	49	51
52 ± 0,1	[mm]	32	34	40.6	40.8
33 min.	[mm]	6	7	9	10
1	[mm]	20	23	23	29
2	[mm]	8.5	12	10	17
i2 -0,05	[mm]	4	5	6	6
		2	3	0	0
13	[mm]			4 0 . 4 5 9	4 0 4 5 0
14	[mm]	0.9×45°	1 x 45°	1.3x45°	1.3×45°
/1 x v2	[mm]	M5 x 10	M5 x 10	M8 x 17	M8 x 17
Ø v3	[mm]	5.5	5.5	8.5	8.5
	[mm]	M5	M6	M6	M8
Vith pneumatic clamping monitoring Version w	ith cover	•			
Part no short clamping lever		1801 110	1802110	1803110	1804110
Veight, approx.	[kg]	0.3	0.53	0.92	1.17
Part no long clamping lever (blank)	[1/9]	1 <b>801 130</b>	1802 130	1803130	1804130
	الحما	0.57	0.88	1.4	1.7
Veight, approx.	[kg]	1 <b>801 150</b>	1802 150	1803150	1804150
Part no universal clamping lever	[[]				
Veight, approx.	[kg]	0.32	0.57	0.93	1.06
ersion without cover**					
Part no short clamping lever		1801 111	1802111	1803 111***	1804111
Veight, approx.	[kg]	0.27	0.46	0.82	1.03
Part no long clamping lever (blank)	. 01	1801 131	1802 131	1803 131***	1804131
Veight, approx.	[kg]	0.54	0.82	1.3	1.56
Part no universal clamping lever	191	1801 151	1802 151	1803 151***	1804 151
Veight, approx.	[kg]	0.29	0.51	0.83	0.92
	[1/9]	3.20	0.01	0.00	0.02
Vith pneumatic unclamping monitoring					
Part no. (version see above)		1801 1XXA	18021XXA	18031XXA	18041XXA
Vithout position monitoring					
		18011XXB	18021XXB	1803 1XXB	18041XXB
Part no. (version see above)		IOUTIAAD	IOUZ IAAD	1009 IVVD	1004 IAAB
Accessories					
Part no short clamping lever		3548 1121	35481122	35481123	3548 1124
Part no long clamping lever (blank)		3548 1071	3548 1072	35481073	3548 1074
Part no universal clamping lever		3548 4111	35484112	35484113	35484114
Screw for universal clamping lever	[mm]	M5x30 -12.9	M5x30 -12.9	M8 x 35 -12.9	M8 x 35 -12.9
Fightening torque	[Nm]	10	10	42	42
	[i vi i i]				3301 468
Part no.		3301 1019	3301 1019	3301 468	

<sup>\*\*</sup> use screw material12.9; \*\*\* max. operating pressure 200 bar

## **Short clamping lever**



## Universal clamping lever



## Calculation of the clamping force

## Clamping lever length e is known

**1.1** Admissible clamping force as a function of the clamping lever length e

$$F_{adm} = \frac{A}{e - B}$$
 [kN]

1.2 Admissible operating pressure

$$p_{adm} = \frac{F_{adm} * 100}{C} \left( \frac{e - B}{D} + 1 \right) \quad [bar]$$

1.3 Effective clamping force at other

**1.3.1**  $F_{adm} = and p_{adm}$  are known

$$F_{sp} = F_{adm} \frac{p}{p_{adm}} \le F_{adm}$$
 [kN]

1.3.2 In general

$$F_{sp} = \frac{C}{\left(\frac{e-B}{D}+1\right)_* 100} * p \le F_{adm} \qquad [kN]$$

Maximum clamping lever length depending on the existing operating pressure

$$e_{\text{max}} = \frac{A}{(C * 0.01 * p) - E} + B \quad [mm]$$

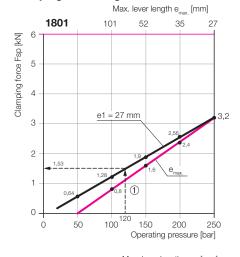
F <sub>sp</sub> , F <sub>adm.</sub>	= Clamping force	[kN]
e, e1, e <sub>max.</sub>	= Clamping lever length	[mm]
p, p <sub>adm.</sub>	= Operating pressure	[bar]
AE	= Constants as per chart	

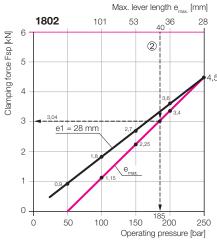
Enter the variables in the above units into the formulas

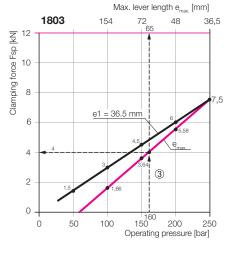
## Constants

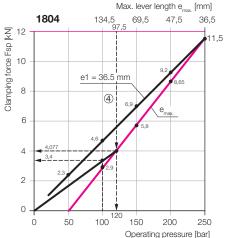
Size	1801	1802	1803	1804
Α	80	112.5	251.3	385.3
В	2	3	3	3
С	1.594	2.262	3.888	5.718
D	101.7	97.62	113	138.1
E	0.787	1.152	2.224	2.789

## Clamping force diagrams









Example 1 Compact clamp 1801 110 Series clamping lever e1 = 27 mm  $F_{adm} = 3.2 \text{ kN}$  at  $p_{adm} = 250 \text{ bar}$ Operating pressure p = 120 bar

Effective clamping force 
$$F_{\text{Sp}} = \quad F_{\text{adm}} \, \frac{P}{\rho_{\text{adm}}} = 3.2 \, \frac{120}{250} = 1.536 \, \text{kN}$$

$$F_{sp} = \frac{C}{\frac{(e-B+1)*100}{D}*100}*p$$

$$F_{sp} = \frac{1.594}{\frac{(27-2*1)*100}{(101.7*1)*100}}*120$$

$$F_{sp} = 1.535 \text{ kN}$$

Example 2 Compact clamp 1802110 Series clamping lever e = 40 mm

$$\begin{array}{ccc} \text{Admissible clamping force} \\ \text{F}_{\text{adm}} = & \frac{A}{e-B} = \frac{112.5}{40-3} = 3.04 \text{ kN} \end{array}$$

Admissible operating pressure 
$$p_{adm} = \frac{F_{adm} * 100}{C} * \left(\frac{e-B}{D} + 1\right)$$

$$p_{adm} = \frac{3.04 * 100}{2.262} * \left(\frac{40-3}{97.62} + 1\right)$$

Example 3 Compact clamp 1803110 Operating pressure p = 160 bar Special clamping lever

Maximum clamping lever length
$$e_{max} = \frac{A}{(C * 0.01 * p) - E} + B$$

$$e_{max} = \frac{251.3}{(3.888 * 0.01 * 160) - 2.224} + 3$$

$$e_{max} = 65.875 \text{ mm} \rightarrow 65 \text{ mm}$$

$$\label{eq:maximum clamping force} \begin{split} & \text{Maximum clamping force} \\ & \text{F}_{\text{Sp}} = \begin{array}{c} \frac{C}{\left(\frac{e-B}{D}+1\right)\,\star\,100}\,\star\,p \\ & \text{F}_{\text{Sp}} = \begin{array}{c} \frac{3.888}{\left(\frac{B5-3}{113}+1\right)\,\star\,100}\,\star\,160 \\ & \text{F}_{\text{Sp}} = \end{array}\,\star\,4\,\text{kN} \end{split}$$

Example 4 Compact clamp 1804110 Special clamping lever e = 97.5 mm

Admissible clamping force 
$$F_{\text{adm}} = \ \frac{A}{e-B} = \frac{385.3}{97.5-3} = \ 4.077 \ \text{kN}$$

Admissible operating pressure 
$$p_{adm} = \frac{F_{adm} * 100}{C} * \left(\frac{e-B}{D} + 1\right)$$

$$p_{adm} = \frac{4.077 * 100}{5.718} * \left(\frac{97.5 - 3}{138.1} + 1\right)$$

 $p_{adm} = 120 bar$ 

$$\begin{split} & \text{Effective clamping force at 100 bar} \\ & F_{Sp} = \begin{array}{c} C \\ \frac{\left(e-B+1\right) \times 100}{D+1 + 1 \times 100} \times p \\ \\ & F_{Sp} = \begin{array}{c} \frac{5.718}{\left(\frac{97.5-3}{138.1}+1\right) \times 100} \times 100 \\ \\ & F_{Sp} = \end{array} & 3.4 \text{ kN} \end{split}$$

## Admissible Flow Rate Important Notes

#### Admissible flow rate

The admissible flow rate as per the chart on page 3 refers to the "short" clamping lever. Thus the clamping time is approx. 0.6 seconds and the unclamping time approx. 1 second. Longer clamping levers with larger mass moments of inertia cause higher loads on the swing mechanism, which results in higher wear. The end stop during unclamping is also critical. Therefore, the flow rate should be reduced with longer clamping levers according to the following formula:

$$Q_{L} = Q_{k} * \sqrt{\frac{J_{k}}{J_{l}}} cm^{3}/s$$

Q<sub>L</sub> = Adm. flow rate with longer special clamping lever

 $Q_{\rm K} =$  Adm. flow rate with "short" clamping lever as per the chart on page 3

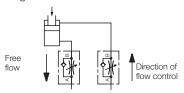
J<sub>K</sub> = Moment of inertia of the "short" clamping lever (see chart)

J<sub>L</sub> = Moment of inertia of the special clamping lever

$$\label{eq:clamping_loss} \text{Clamping time } t_{s_p} = \frac{ \text{ Oil volume clamping } [\text{cm}^3] }{ \text{Adm. flow rate } \frac{[\text{cm}^3]}{\text{e}} } \left[ s \right]$$

## Throttling of the flow rate

A flow rate throttling has to be effected in the supply line to the compact clamp. This avoids a pressure intensification and thereby pressures exceeding 250 bar.



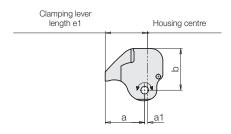
## Determine the moment of inertia

Due to the complicated shape of the clamping levers, the mass moment of inertia can only be determined with the help of a CAD model in the computer.

Attention! The clamping lever length e always starts from the centre of the housing. As the examples show, the swing axis for determining the moment of inertia is offset by 1-2 mm. The exact position of the swing axis can be determined with the coordinates a and b.

#### Short clamping lever

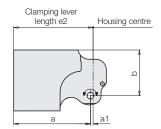
The moment of inertia in the chart is the starting point for the maximum flow rate and the shortest possible clamping time.



Size		1	2	3	4
e1	[mm]	27	28	36.5	36.5
а	[mm]	26	26	34.5	34.5
a1	[mm]	1	2	2	2
b	[mm]	25.5	27.5	33	36
Moment of inertia J <sub>K</sub>	[kgmm²]	22	34	98	125

#### Long clamping lever (blank)

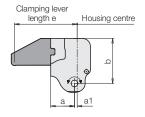
The blank is not a finished clamping lever. The value in the chart shows how high the maximum moment of inertia can rise.



Size		1	2	3	4
e2	[mm]	59	60	67.5	67.5
а	[mm]	58	58	65.5	65.5
a1	[mm]	1	2	2	2
b	[mm]	34.5	34.5	33	36
Moment of inertia J <sub>L</sub>	[kgmm²]	576	756	1234	1477

#### Universal clamping lever

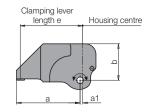
The universal clamping lever is supplemented by clamping arm provided by the customer and the fixing screw. A CAD model should be created in the assembled state to determine the moment of inertia.



Size		1	2	3	4
е	[mm]	Cu	istome	er requ	est
а	[mm]	16	18	20	20
a1	[mm]	1	2	2	2
b	[mm]	34.5	38.5	42	50
Moment of		Unive	rsal cla	amping	j leve
inertia J <sub>L1</sub>	[kgmm <sup>2</sup> ]	49	97	170	294
+ extension J <sub>L2</sub>	[kgmm²]	W		rmine D mod	el

## One-piece special clamping lever

A one-piece special clamping lever can only be manufactured at Römheld because exact contours are required for the swing mechanism and the pneumatic position monitoring.



Size		1	2	3	4	
е	[mm]	Cı	ustome	er requ	est	
а	[mm]	Cı	ustome	er requ	est	
a1	[mm]	1	2	2	2	
b	[mm]	25.5	27.5	33	36	
Moment of inertia J <sub>L</sub>	[kgmm²]	Determine gmm²] with CAD model				

#### Important notes

The compact clamps are designed exclusively for clamping of workpieces in industrial applications.

Hydraulic clamping elements can generate considerable forces. The workpiece, the fixture or the machine must be in the position to compensate these forces.

In the effective area of clamping lever there is the danger of crushing. The manufacturer of the fixture or the machine is obliged to provide effective protection devices.

During loading and unloading of the fixture a collision with the clamping lever has to be avoided. Remedy: Mount position adaptor.

The height of the flange surface of the compact clamp and the height of the clamping surface on the workpiece should be matched so that the clamping height is approximately in the middle of the usable clamping stroke.

The compact clamp has to be checked regularly on contamination by swarf and has to be cleaned.

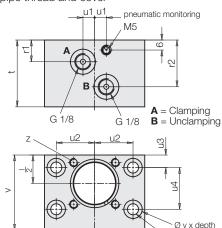
For dry machining, minimum quantity lubrication and in case of accumulation of very small swarf or particles, regular disassembly, cleaning and lubrication of the lever mechanism as per operating manual is required.

Operating conditions, tolerances and other data see data sheet A 0.100.

## Mounting Body Pneumatic Position Monitoring

## **Mounting body**

for version with pipe thread and cover



#### Pneumatic position monitoring

## 1. Pneumatic clamping monitoring

In the clamping area, the clamping lever slides downwards at two hardened surfaces of the body. In one of the surfaces there is the bore hole for the pneumatic clamping monitoring.

The clamping lever overruns the bore hole, but does not completely close it. Only when the workpiece is really clamped, the clamping lever supports itself on the sliding surface and the bore hole will be firmly closed.

The clamping monitoring signals:

- The clamping lever is in the usable clamping range and
- a workpiece is clamped.

#### Important note

Required minimum pressures for clamping monitoring:

Hydraulics 70 bar Pneumatics 3 bar

## 2. Pneumatic unclamping monitoring

In the unclamping position the clamping lever closes a pneumatic bore hole.

## Important note

The compact clamp is available with "clamping monitoring" or "unclamping monitoring". The control of both positions is not possible since the minimum dimensions of the housing allow only one pneumatic connection.

## Monitoring by pneumatic pressure switch

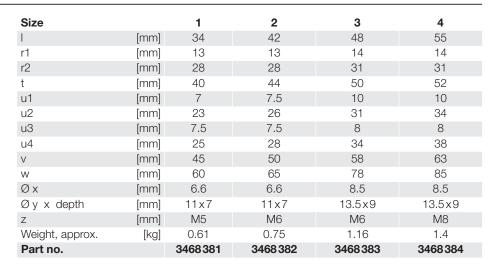
For the evaluation of the pneumatic pressure increase standard pneumatic pressure switches can be used.

With one pressure switch up to 8 compact clamps can be controlled.

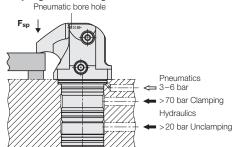
## Important note

Pneumatic position monitorings are only process-safe, when air pressure and air volume are precisely adjusted.

For measuring the air volume, appropriate devices are available. Please contact us.



## Clamping monitoring



## Example for clamping position

Required switching pressure 4.5 bar Pressure drop, if 1 compact

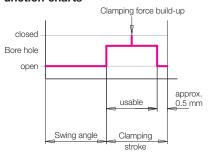
clamp is not clamped approx. 2 bar

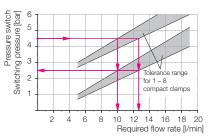
As per diagram:

Required flow rate approx. 10-13 l/min (depending on the number of

connected compact clamps)

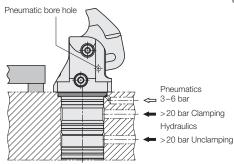
## **Function charts**





Required flow rate depending on the switching pressure of the pneumatic pressure switch for a pressure drop  $\Delta p$  2 bar

## Unclamping monitoring



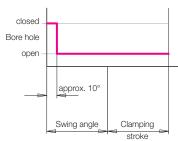
#### Example for unclamping position

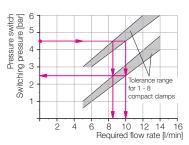
Required switching pressure 4.5 bar Pressure drop, if 1 compact

clamp is not unclamped approx. 2 bar

As per diagram:

Required flow rate approx. 8.5–10 l/min (depending on the number of connected compact clamps)





Required flow rate depending on the switching pressure of the pneumatic pressure switch for a pressure drop  $\Delta p$  2 bar

